



**Sharif University of Technology  
School of Mechanical Engineering  
Center of Excellence in Energy Conversion**

# **Advanced Thermodynamics**

## **Lecture 11**

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∅ Heat engine performance index:

$$h_{th} = \frac{W}{Q_H} = \frac{Q_H - Q_L}{Q_H} = 1 - \frac{Q_L}{Q_H}$$

$$\left( S_{gen} = \frac{Q_L}{T_L} - \frac{Q_H}{T_H} \right) \rightarrow h_{th} = 1 - \frac{T_L}{T_H} - \frac{T_L S_{gen}}{Q_H}$$

∅ Observations:

$$S_{gen} = 0 \quad (\text{reversible, internally})$$

$$S_{gen} \neq 0 \quad h < h_c \quad (\text{reversible heat engine})$$

∅ Rewrite 2<sup>nd</sup> law:

$$Q_L = \frac{T_L}{T_H} Q_H + T_L \cdot S_{gen}$$

∅ For fixed  $Q_H$ ,  $T_L$ , and  $T_H$ , , entropy production causes an increase in  $Q_L$  , from the 1<sup>st</sup> law, a decrease in  $W$  then follows.

∅ For fixed  $Q_H$ ,  $Q_L$ , and  $T_H$ , , an increase in entropy production must be accomplished by a decrease in the low temperature,  $T_L$ .

∅ Influence of temperature on performance

$$h_{th} = 1 - \frac{T_L}{T_H} \rightarrow \frac{\partial h_c}{\partial T_H} = \frac{T_L}{T_H^2}$$

$$\frac{\partial h_c}{\partial T_L} = -\frac{1}{T_H}$$

∅ Since  $\frac{\partial h}{\partial T_H} > 0 \Rightarrow h \uparrow$  when  $T_H \uparrow$

∅ since  $\frac{\partial h}{\partial T_L} < 0 \Rightarrow h \downarrow$  when  $T_L \uparrow$

- ∅ Key to performance for any heat engine
  - ∅ Minimize entropy production (generation),  $S_{gen}$
  - ∅ Raising  $T_H$
  - ∅ Lowering  $T_L$
- ∅ Optimization techniques
  - ∅ Objective function: including all system parameters
  - ∅ Constraints, for example  $S_{gen} \geq 0$  and  $T_H, T_L \geq 0$
  - ∅ 2<sup>nd</sup> law optimization or entropy generation minimization

Ø Heat engine with variable temperature heat transfer:

$$h_{th} = 1 - \frac{\dot{Q}_L}{\dot{Q}_H} = 1 - \frac{1}{\dot{Q}_H} [\dot{m}_L C_L (T_{L2} - T_{L1})] =$$

$$1 - \frac{1}{\dot{Q}_H} \left\{ \dot{m}_L C_L \left[ T_{L1} \exp \left( \frac{1}{\dot{m}_L C_L} (\dot{S}_{gen} - \dot{m}_H C_H \ln(T_{H2}/T_{H1})) \right) - T_{L1} \right] \right\}$$

$$\Rightarrow h_{th} = 1 + \frac{\dot{m}_L C_L T_{L1}}{\dot{Q}_H} - \frac{\dot{m}_L C_L T_{L1}}{\dot{Q}_H} \left[ 1 - \left( \frac{T_{H2}}{T_{H1}} \right)^{\frac{\dot{m}_H C_H}{\dot{m}_L C_L}} \right]$$

$$h_{th} = 1 + \frac{\dot{m}_L C_L T_{L1}}{\dot{Q}_H} \left[ 1 - \left( \frac{T_{H2}}{T_{H1}} \right)^{\frac{\dot{m}_H C_H}{\dot{m}_L C_L}} \right]$$